ANLY ELECTRONICS CO., LTD.

AT03 PID Temperature Controller User's Manual

AT - 403 / AT - 503 / AT - 603 / AT - 703 / AT - 903



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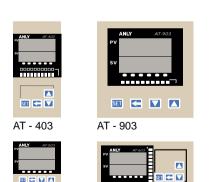
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Chapter 0 : Overview

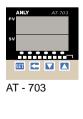
ANLY AT03 series is an 1 input, 2 output, 3 alarm, auto-tuning PID temperature controller designed to accommodate comprehensive needs in process automation and system integration.

Wide ranges of inputs are accepted, including thermocouple (T/C: type K, J, T, R, E, S, B, N), Resistive Temperature Device (RTD: Pt100, JPt100) and linear input (voltage, current). Up to 2 output controls include relay, SSR, linear voltage, linear current and signal retransmission. Servo motor control is also possible. Up to 3 alarms are available and each has different functions and modes for customizations. This controller can have up to 8 segments for a single process.

A separate optionsl channel allows Remote Set Point via linear voltage or linear current. The same channel can also be used for current transformer for heater break alarm. The users may chose between RS-232 and RS-485 communication modules for links up with computer for programming.



AT - 603



AT - 503

Chapter 1: Specification

Detaile Information

Detail Specification						
Туре	AT - 403 / AT - 503 / AT - 603 / AT - 703 / AT - 903					
Operating voltage	100 ~ 240VAC					
Rated Frequency	50 / 60 Hz					
Power Consumption	Approximately 3.5VA					
Sensor input	Thermocouple: K, J, T, R, E, S, B, N					
	RTD: Pt100, JPt100					
	Linear : Voltage, Current					
Control output	Relay, Voltage, Linear, Motor Control					
Alarm output	250VAC, 5A					
Alarm fucntion	See Table on Page 49					
Control method	PID, PI, P, On/OFF, Dead band					
Setting	Digital setting with front keys					
Communication	RS-232 or RS-485 (both optional)					
Indicator	4-digit 7-segment-display					
Ambient temperature	-10°C ~ +50°C					
Storage temperature	-25°C ~ +65°C					
Ambient humidity	34%~80% relative humidity with no icing or condensation					
Storage humidity	35%~95% relative humidity with no condensation					

Detail Specification (Continue)					
Weight	AT-403: ~170g				
(only approximation, actual figures varie depending on the options chosen)	AT-503: ~125g				
	AT-603: ~170g				
	AT-703: ~200g				
	AT-903: ~250g				

Detail Features						
Measuring accuracy	Within 0.3% of present value or +-2OC, whichever is greater					
Propotional Band	0.0 ~ 3000 sec (0.1 sec increment)					
Integral Time	0 ~ 3600 sec (1 sec increment)					
Derivative Time	0 ~ 900 sec (1 sec increment)					
Control Period	0 ~ 150 sec (1 sec increment)					
Sampling Period	300ms					
Memory Protection	EEPROM non-volatile memory (at least 100,000 write cycle)					

Ordering Information

ANLY AT03 can be customized to specific needs and requirements. The ordering code consists of a 10-digit numeral in 3-4-3 format:

AT- 03- 00 - 00

"03" is the designation for AT03 series controllers. The following explains the representation of the remaining 8 numerals.

	- 🗆 🛭] - 🗌 [
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Dimension
4 = 96x48mm (1/8 DIN)
5 = 48x48mm (1/16 DIN)
6 = 48x96mm (1/8 DIN)
7 = 72x72mm
9 = 96x96mm (1/4 DIN)

The dimension size is a measurement for the device face plate. Note that AT-402 is vertical while AT-603 is horizontal, although they have the same DIN size.

AT- 03- **I** 0 - 0 0

Input
1 = T/C or RTD
2 = 0~100mV
3 = 0~20mA
4 = 4~20mA
5 = 0~5V
6 = 0~10V
7 = 1~5V
8 = 2~10V
9 = 0~1V

1 is for both thermocouple and RTD sensor inputs. However, the sensor type also needs to be specificied by users under Level menu. 2 through 9 are for linear inputs.

AT- 🗌 03- 🔲	
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Output 1	Output 2
(1 is standard)	0 = None
1 = Relay	1 = Relay
2 = Pulsed	2 = Pulsed
3 = 0~20mA	3 = 0~20mA
4 = 4~20mA	4 = 4~20mA
5 = 0~5V	5 = 0~5V
6 = 0~10V	6 = 0~10V
7 = 1~5V	7 = 1~5V
8 = 2~10V	8 = 2~10V
9 = Motor Contr	ol

A relay output on Ouput 1 is standard on all AT03. It can be changed to any of the 9 types. Note that motor control on Output 1 uses 3 terminals. Therefore, Motor Control option is not available with Output 2. Therefore, "90" is the code for motor controlo output.

AT-	□ 0 3	- 🗌		-		

Alarm					
1 = 1 alarm					
2 = 2 alarms					
3 = 3 alarms					
3 = 3 alaitiis					

1 alarm is standard on all AT03. There can be upt o 3 alarms on AT-403, AT-603, AT-703 and AT-903. However, AT-503 can only have up to 2 alarms.

A T - □ 0 3 - □ □ □ □ - ■ □ □
Other
0 = None
1 = DC 24V
2 = Current Transformer
A = Remote Set Point 0~20mA
B = Remote Set Point 4~20mA
C = Remote Set Point 0~5V
D = Remote Set Point 0~10V
E = Remote Set Point 1~5V
F = Remote Set Point 2~10V

In Other option, there can be inputs for DC24V, current transformer and Remote Set Point (R-SP). Current transformer is used as the heater break alarm. R-SP is used to change SV remotely with volatage or current. AT-403 is availiable with Other option but this will negate Ouput2.

Communication 0 = None 1 = RS-485

AT- 03-

2 = RS-232

Communication module, such as RS-232 and RS-485 module, is available for direct link up with PC for programming.

Program is the option that gives the controller segment programming.

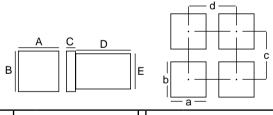
Some models, due to their limited terminals, cannot be ordered with all the features. Such limitations are:

AT-503 is not available with the Other and the 3 alarms options. Also, AT503 only uses two terminals for its RS-485 communication while others use three terminals

Servo motor control option occupies one Output 2 terminal. Hence, the Motor Control and Output 2 are not available on the same device.

An example of order code is AT - 903 - 1111 - 000. It would have 1/4 DIN size, a sensor input, 2 relay outputs, 1 alarm, no Other option, no Communication option and no Program Control options

Chapter 2 : Installation



	Device Measurement				Panel	Cutout N	∕leasure	ement	
Type	Α	В	O	ם	Е	а	b	C	d
AT-403	48	96	10.5	83	90	46+0.5	91+0.5	120	70
AT-503	48	48	10.5	83	45	46+0.5	46+0.5	70	70
AT-603	96	48	10.5	83	43	91+0.5	46+0.5	70	120
AT-703	72	72	10.5	83	67	68+0.5	68+0.5	100	100
AT-903	96	96	10.5	83	90	91+0.5	91+0.5	120	120

All measurements in millimeter (mm)

Mounting Procedure

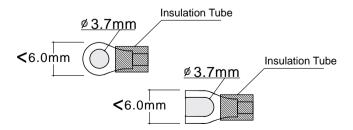
- Make sure the front panel is no more than 10mm thick. Also, each of the two brackets needs additional 6mm clearance outside of the shell casing on each side.
- 2. Make a panel cut-out precise to the measurement according to the type. (see the table on the previous page)
- 3. Insert the controller into the cutout from the front side of the panel



- Align the bracket so the notches are in their slots and the wide side towards the front panel.
- 5. Pinch the prongs and slide the bracket forward till the bracket is firmly against the backside of the front panel.
- 6. Repeat step 3 through 5 with another bracket on the other side.

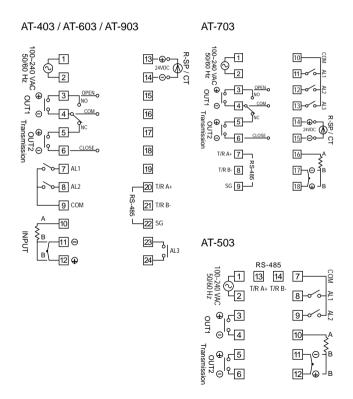
Terminals

For wire terminations, the recommended terminals are fork or ring terminals with #6 stud size, narrow tongue, and with insulation. Wire gauge should be at least AWG 18.



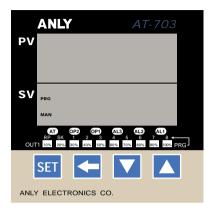
Of all 5 types of ANLY AT03, there are 3 styles of terminal arrangements. AT-503 has 14 usable terminals; AT-403/603/903 have 19 usable terminals; AT-703 has 18 usable terminals. Each terminal has numbering on the edge of the casing for easy identification.

The terminal layout for different models are as followed.



Chapter 3: Programming

Terminology



- PV Process value display
- SV Set value display
- PRG Programmable mode indicator
- MAN Manual mode indicator
- AT Auto tuning indicator
- OP2 OP1 Control output 2, 1 indicator
- AL3 AL2 AL1 Alarm output 3, 2, 1 indicator
- _{10%} ~ _{100%} Manipulated output display
- 1 ~ 8 Segment-in-process display
- RP Soaking mode indicator
- SK Ramping mode indicator

SET Set Key

used to navigate within the hierarhal set-up menu

Shift Key

used to shift in and out of the adjust mode

Down Key

used to decrease a value or to scroll down. When not in programming mode, press-and-hold to call up lock or hold function.

Up Key

used to increase a value or to scroll up.

When not in programming mode, press-and-hold to go back to the standby display.

Press-and-Release

press a key and release it immediately

Press-and-Hold

press a key and hold it untill the display has changed

Menu mode

a heirarchal tree menu with the PV display showing the menu title and the SV display showing the submenu or the parameter.

Adjust mode

when the value at the SV diaply is flashing and ready to be adjusted with the down or up button.

Standby mode

when the red PV display is sowing the temperature's present value and the SV display is showing the set value. At this mode, the controller can ne changed to Menu mode or Operation mode.

Operation mode

when the device is running

Power-up Sequence

When the controller is powered up, it goes through 4 diagnostic stages.



1st stage: All displays light up. Users can verify that all display LEDs are functional.



2nd stage: The PV display shows Input1 and the SV display shows the temperature unit used, C. for Celsius and F. for Fahrenheit. Following the unit is the sensor type and range.



3rd stage: The displays show the range of temperature according to the chosen sensor type and range. PV display shows the minimum and the SV display shows the maximum



4th stage: The controller goes to the standby mode and the device is operational.

Hierarchal Tree Menu

ANLY AT03 has a hierarchal tree menu to organize the parameters and functions. There are 7 Submenus under Level.

When not in the adjust mode, press-and-hold Set or Up will always bring the device to Standby mode.



User (uSEr) submenu



Control (CntL) submenu



Output (Out) submenu

Ľ	E	<u>''</u>	L
	- 0	5P	Γ

Special Control (SPC) submenu



Input (inP) submenu



Program (ProG) submenu



Hide (HidE) submenu

Device Hold

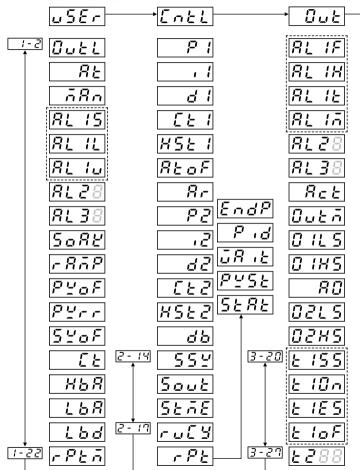
In Standby mode, press-and-hold Down to enter Hold mode. In the Hold mode, the SV display will be flashing HoLd, meaning all operation has been suspended.

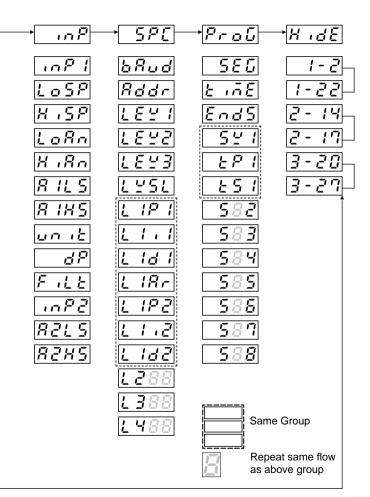
Device Lock

Under Level menu, press-and-hold Down to enter the lock parameter submenu. The parameter is freely adjustable from 0 to 9999. However, only 10 numbers will lock the device in specific ways. The following table details the number and the corresponding table function.

Device Lock Code And Function			
Lock Code	Function		
0	all parameters are locked except PV		
101	all parameters are locked except SV		
11	open "USER" level and above		
22	open "CNTL" level and above		
111	open "OUT" level (except OUTM) and above		
222	open "INP" level and above		
1100	open "SPC" level and above		
2200	open "PROG" level and above		
1122	open "HIDE" level and above		
1234	open "USER" and "PROG" level only		

Parameter Flow Chart





Parameter Description, Range, Initial Value

Process Value LoSP ~ HiSP

LoSP ~ HiSP

0.0

<u>u5E</u>r USER submenu

(Parameter) (Range) (Initial Value)

CutL OutL

Set Value

Output level percentage 0.0 ~ 100.0% 0.0

Auto tuning No / Yes No

Man

Manual Mode Man1 = power failure memory No Man2 = no memory No = non

Alarm 1 Set Value $\begin{array}{ccc} & \text{AL1F} = 1,2 & \text{AL1S} = -200 \sim 200 & 10.0 \\ & \text{AL1F} = 3,4 & \text{AL1S} = \text{Losp} \sim \text{Hisp} \\ & \text{AL1F} = 10 & \text{AL1S} = 1 \sim 8 \text{ segment} \end{array}$

USER submenu
(Parameter)

(Range)

(Range)

(Range)

Alarm 1 Lower Set Value

0 ~ 200

AL1u

Alarm 1 Upper Set Value 0 ~ 200 10.0

For AL2* and AL3*: please refer to the AL1* description above

Soak

Soak Operation (only when AL1M= 8 or 9) 0.0 ~ 99.59 hr.min 0.00

"SoAK" only performs when AL1M is set at 8 or 9, and the controller is without program function. If AL1M is set at 8, AL1 will shift to soak function and the contact is normally open; if AL1M is set at 9, AL1 will shift to soak function and the contaact is normally closed.

Ramp Operation 0.0 ~ 200.0 per minute 0.0

"rAmP" sets the rate of change for PV when the controller is without program function. For example, if ramp is set at 10, the PV will increase 10 degree per minute. However, if PV is higher than SV, the PV will decrease 10 degree per minute.

(Initial Value)

10.0

<u>u5E</u>r USER submenu

(Parameter) (Range) (Initial Value)

PVoF

PV Offset -200 ~ 200 0

If PV is not correct to SV, PV can be offset linearly with positive or negative pvof .

PVrr

PV Ratio 0.001 ~ 9.999 1.000

If PV is not correct to SV, PV can be adjusted with "pvrr". The formula is:

PV (now) - PV (pre) * pvrr + pvof



540F SVoF

SV Offset -200 ~ 200 0.0

If SV is not correct to PV, SV can be offset linearly with positive or negative "SVoF" .

Current Transformer Monitor 0.0 ~ 100.0 A 0.0

"Ct" is used to detect if the heater is broken. The value ranges from 0.0A ~ 100.0A. ("Ct" is only availiabe if the option is ordered)

⊔5Er USER submenu

(Parameter) (Range) (Initial Value)

₩₽₽ HbA

Heater Break Alarm Value 0.1 ~ 100.0 A 0.1

"Hba" ranges from $0.1A \sim 100.0A$. For example, when the control output is on and "Ct" <= "Hba", the heater is broken. The alarm is triggered. Or when the control output is off and "Ct" >= "Hba", the alarm is then triggered. ("Hba" is only available if the option is ordered)

<u>Ļ</u> <u>Ļ</u> ∏ LbA

Loop Break Alarm Value 0.1 ~ 200.0 min 8.0

上占♂ Lbd

LBA Dead Band 0.0 ~ 200.0 0.0

Parameters for Loop break Alarm. For example, when out1 = 0.0% and "lba" has elapsed, PV should be below "lbd". If PV is till within "lbd", the alarm is triggered. When out1 = 100% and "lba" time has elapsed, PV should be higher than "lbd". if PV is till within "lbd", the alarm is triggered. ("lba" and "lbd" is implemented through firmware only)

rPtm

Repeat Times Monitor (only in Program function) 1 ~ 1000

"rptm" displays how many times the program has repeated thus far. This parameter only works whenthe controller has program function turned on.

Entl CONTROL submenu (Parameter) (Range) (Initial Value) $0.0 \sim 3000$ 30.0 Output 1 Propotional Band i1 $0 \sim 3600 \text{ sec}$ **Output 1 Integral Time** 240 Output 1 Derivative Time $0 \sim 900 \, \text{sec}$ 60 Output 1 Cycle Time $0 \sim 150 \, \text{sec}$ 15 "ct1" is the cycle time for output 1. Normally, it is set at 0 for 4~20mA output, 1 for SSR output and 15 for relay output. |#5<u>|-</u> || HSt1 Output 1 Hysteresis $0.0 \sim 200.0$ 0.0 REOF AtoF **Auto Tuning Offset** -200 ~ 200 0.0 Anti-Reset Windup 0.0 ~ 100.0 % (SV-P1*Ar) 100.0



CONTROL submenu

(Parameter)

(Range)

(Initial Value)

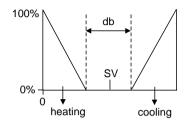
"Ar" is for preventing over-shooting. This parameter sets an integral delay. The setting ranges from 0 ~ 100%. At 100%, the integral will perform when PV reaches the propotional band. At 50%, the integral will perform when PV reaches 50% of the propotional band.

P 2 P2		
Output 2 Propotional Band	0.0 ~ 3000 sec	30.0
12 i2		
Output 2 Integral Time	0.0 ~ 3600 sec	240
₫ ₫ d2		
Output 2 Derivative Time	0.0 ~ 900 sec	60
[<u>[</u>		
Output 2 Cyclic Time	0 ~ 150 sec	15
H5 E Z HSt2		
Output 2 Hysteresis	0.0 ~ 200.0	0.0
db		
Dead Band / Overlap	-200.0 ~ 200.0	0.0



CONTROL submenu

(Parameter) (Range) (Initial Value)



55<u>9</u> ssv

Soft Start Set Value 0.0 ~ 200.0 120.0

"SSV" is used to prevent the heating system temperature rising too quickly at the start. For example, to achieve 120 degree slowly, "SSV" is set at 120.

Sout Sout

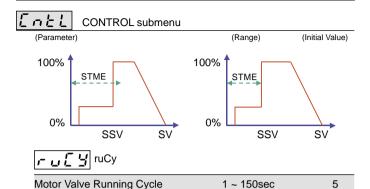
Soft Start Output Percentage 0.0% ~ 100.0 % 30.0

"Sout" sets the output percentage when PV is under "SSV".

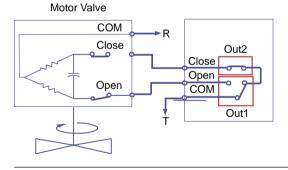
5 <u>5 5 5</u> Stme

Soft Start Fail Time 0 ~ 10 min 10

"Stme" sets the time interval when the soft start is deemed failed. When the "Stme" time is reached and the PV has not reached "SSV", the soft start has failed and the controller will revert to SV.



"ruCy" sets the running cycle time in motor valve control, the time from close to open or from opento close.



,- 		
Program Repeat Time	1 ~ 1000	1

"rPt" set the number of times the program will repeat execution.



CONTROL submenu

(Parameter) (Range) (Initial Value)

"StAt" sets the start mode the program. "CoLd" requires manual start. "rSET" starts the program automatically after the power is turned on. "Hot" starts from memory after a power failure.

 $\begin{array}{ll} \text{Start Point Selection} \stackrel{\text{(only in Program mode)}}{\text{PV}} & \text{rSEt} = \text{start from 0} & \text{rSEt} \\ & \text{PV} = \text{start from PV} \end{array}$

□ □ □ WAit

Wait Value in Program 0.0 ~ 200.0 0.0

"wAit" sets the time the SV will wait for PV if PV chanes slower than SV.

Pid Pid

PID / Level PID Selection Pid = PID Pid LPid = Level PID

"Pid" selects between PID (Pid) and Level PID (LPid). Level PID allows upto 4 level of different PID.

[ntl

CONTROL submenu

(Parameter)

(Range)

(Initial Value)

EndP EndP

End of Program Control

Cont = Continuous StoP = 1 program only StoP

"EndP" controls the the flow of the program to be continuous (Cont) or 1-program-only-and-stop (StoP).

Out

OUTPUT submenu

(Parameter)

(Range)

(Initial Value)

Alarm 1 Action Function

0 ~ 13

1

Please refer to Chapter 6: Alarm for functio descriptions

Out

Alarm 1 Hysteresis

 $0.0 \sim 200.0$

0.0

Alarm 1 in Program Mode on Time

0.00 ~ 99.59 hr.min

0.00

Alarm 1 Special Mode Selection

1 ~ 11

0

Please refer to Chapter 6: Alarm for mode descriptions

OUTPUT submenu

(Parameter) (Range) (Initial Value)

AL2F AL2H AL2t AL1M

RL∃B AL3F AL3H AL3t AL3M

For AL2 and AL3, please refer to Al1 description above.

Act

Control Action Selection CooL / HEAt HEAt

Cutm Cutm

Output Mode Selection (Please contact distributor for changes)

Please refer to Chapter 5 : Output for mode descriptions

[] / 5 O1LS

Output 1 Scale Low 0.0 ~ 100.0 % 17.6

[] | H 5 O1HS

Output 1 Scale High 0.0 ~ 100.0 % 96.0

AO 🗓 🤼

Analog Output Selection PV = transmit PV PV SV = transmit SV dEV = transmit (PV-SV) MV = transmit output percentage

OUTPUT submenu

(Parameter) (Range) (Initial Value)

[] 2 L 5 O2LS

Output 2 Scale Low 0.0 ~ 100.0 % 17.6

[] 2 H 5 O2HS

Output 2 Scale High 0.0 ~ 100.0 % 96.0

Time Signal 1 Start Segment Setting 1 ~ 8 1 (only in Program mode)

"t1SS" sets the segment the alarm will be activated. For example, if the alarm activation is desired in Segment 2, set "t1SS" at 2.

Է ¦ቪդ t10n

Time Signal 1 On Time Setting 0.00 ~ 99.59 hr.min 0.01 (only in Program mode)

"t1On" sets the time the alarm will be activated. For example, if the alarm activation is desired after 3 minute in Segment 2, set "t1On" at 3min and "t1SS" at 2. Note that the Program Time in Segment 2 (tP2) may be longer than 3 minute.

上 155 t1ES

Time Signal 1 End Segment Setting 1 ~ 8 1 (only in Program mode)

But

OUTPUT submenu

(Parameter)

(Range)

(Initial Value)

"t1es" sets the segment the alarm will be deactivaed. For example, if the alarm deactivation is dersired in Segment 6, set "t1ES" at 6.

Time Signal 1 Off Time Setting (only in Program mode)

0.00 ~ 99.59 hr.min

0.01

"t10F" sets the time the alarm will be deactivaed. For example, if the alarm deactivation is desired after 7 minute in Segment 6, set "t10F" at 7min and "t1ES" at 6. Note that the Program Time in Segment 6 may be longer than 7 minute.

t2SS t2On t2ES t2oF

For t2 parameters descriptions, please refer to see t1 parameters (t1SS, t1On, t2ES, t2oF).

un P

INPUT submenu

(Parameter)

(Range)

(Initial Value)

Input 1 Selection

K2

LoSP LoSP

Low Set Point

LoSP ~ HiSP

0.0

INPUT submenu		
(Parameter)	(Range)	(Initial Value)
H ,5P HISP		
High Set Point	LoSP ~ HiSP	400.0
LoAn LoAn		
Analog Input Range Low	-1999 ~ 9999	0.0
H , A ,		
Analog Input High	-1999 ~ 9999	100.0
A IL 5 A1LS		
Analog Inpput 1 Scal Low	0 ~ FFFF	
A IHS		
Analog Input 1 Scale High	0 ~ FFFF	
unit unit		
Unit Selection	°C / °F	°C
₫₽ dP		
Decimal Point	0 / 0.0 / 0.00 / 0.000	0.0

INPUT submenu

(Parameter) (Range) (Initial Value)

F , L & FiLt

Digital Filter 0.001 ~ 1.000 0.900

17 7 2 inP2

Input 2 Selection non = no function non Ct = current transformer

rmSV = remote SV

#215 A2LS

Analog Input 2 Scale Low 0 ~ FFFF

#2#5 A2HS

Analog Input 2 Scale High 0 ~ FFFF

5P[SPECIAL CONTROL submenu

(Parameter) (Range) (Initial Value)

☆芹☆♂ bAud

Baud Rate 2.4K / 4.8K / 9.6K / 19.2K / 38.4K 9.6K

Addr

Address 0 ~ 31 0

575 SPECIAL CONTROL submenu

(Parameter) (Range) (Initial Value)

LEV1

Leve 1 PID Range LoSP ~ HiSP 400

[[[]] LEV2

Level 2 PID Range LoSP ~ HiSP 400

LEY3 LEV3

Level 3 PID Range LoSP ~ HiSP 400

Level PID Selection Monitor 1 ~ 4

Level PID Selection Monitor selects whiche level of PID to be monitored. For example, if Level3 parameters (L3P1, L3P1, L3d1... etc.) are to be monitored, set "LVSL" to 3. Note that PID parameter under CONTROL submenu needs to set at Level PID (LPiD).

Level 1 Propotional Band for Output 1 0.0 ~ 3000 30.0

L 1 , 1 L1i1

Level 1 Integral Time for Output 1 0 ~ 3600 sec 240

5PL SPECIAL CONTROL submenu						
(Parameter)				(Range)		(Initial Value)
<u> </u> L1d1						
Level 1 Derivative Time for Output 1			:1	0 ~ 900 sec		60
<u> </u>						
Level 1 Anti-Reset	Windup)		0.0 ~ 1	00.0 %	100.0
L 172 L1P2						
Level 1 Propotional Band for Output 2		ut 2	0.0 ~ 3000 sec 30		30.0	
[L1i2						
Level 1 Integral Time for Output 2		0 ~ 3600 sec		240		
[
Level 1 Derivative Time for Output 2		0 ~ 900		60		
<u> </u>	L2i1	L2d1	L2Ar	L2P2	L2i2	L2d2
<u> </u>	L3i1	L3d1	L3Ar	L3P2	L3i2	L3d2
<u> 488</u> L4P1	L4i1	L4d1	L4Ar	L4P2	L4i2	L4d2

For Level2, Level3 and Leve4 parameters description, please refer to Level1 parameters (L1P1, L1i1, L1Ar, L1P2, L1i2, L1d2).

Program submenu		
(Parameter)	(Range)	(Initial Value)
5<i>E</i> G SEG		
Program Segment Monitor	1 ~ 8	
₹ • • • • • • • • • • • • • • • • • • •		
Program Countdown Monitor		
End5 EndS		
Program Segment End Setting	1 ~ 8	1
5 <u></u>		
SV in Segment 1	LoSP ~ HiSP	100
₽ ! tP1		
Program Time in Segment 1	0.00 ~ 99.59 hr.min	0.00
<u> </u>		
Soak Time in Segment 1	0.00 ~ 99.59 hr.min	0.00
5 8 2 SV2 tP2 tS2	58 5 SV6 tP6	tS6
583 SV3 tP3 tS3	587 SV7 tP7	tS7
5	5 8 8 SV8 tP8	tS8
5 8 5 SV5 tP5 tS5		

ProD

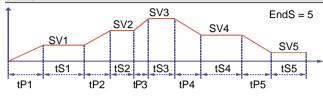
PROGRAM submenu

(Parameter)

(Range)

(Initial Value)

For Segment2 to Segment8 parameters description, please refer to Segment1 parameters (SV1, tP1, tS1).



H .dE

PROGRAM submenu

(Parameter)

(Range)

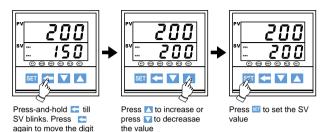
(Initial Value)

Parameters under USER Submenu

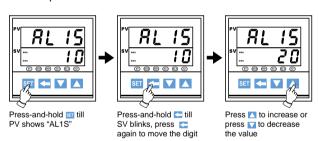
Parameters under CONTROL Submenu

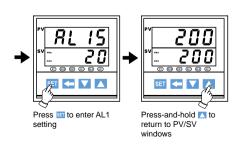
Parameters under OUTPUT Submenu

A. Example: How to set "SV" at 200°C

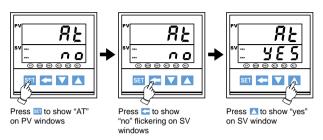


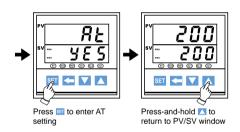
B. Example: How to set AL1S at 20°C





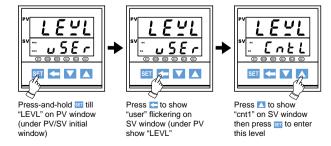
C. Example: How to set "AT" (auto tuning)

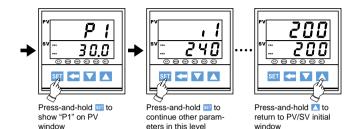




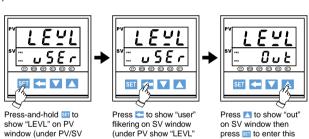
D. Example: How to enter different "level" for setting parameter

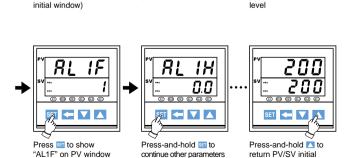
(1) Enter "CntL" level





(2) Enter "Out" level



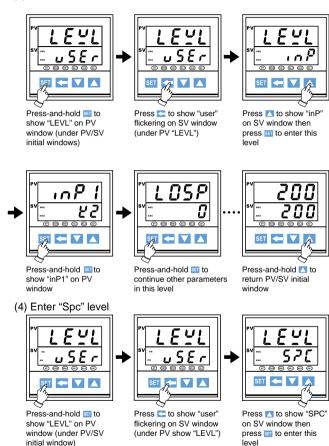


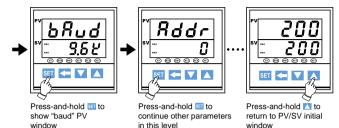
in this level

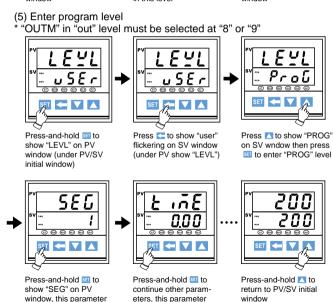
41

window

(3) Enter "inP" level

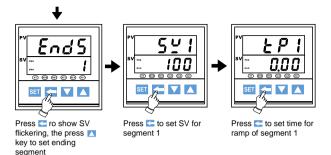


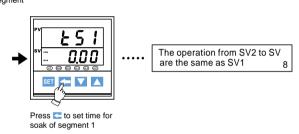




only display executing seament

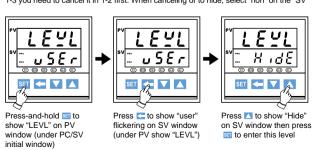
only display time for ramp or soak steps

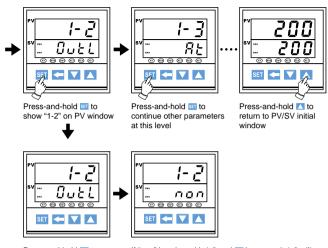




(6) Enter "Hide" level

In this level, the user can arrange parameter order or hiding from No. 1-2 to 1-22, 2-14 to 2-17 and 3-20 to 3-27 (please refer to level parameter flow chart), but same parameter can not be arranged in 2 positions at the same time. For example, to arrange "OUTL" to 1-3 you need to cancel it in 1-2 first. When canceling or to hide, select "non" on the "SV"



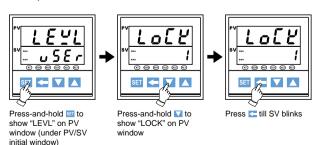


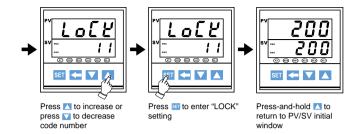
Press-and-hold to show "OUTL" flickering then press to "non" for hiding and cancelling or press to select other parameters

If "non" is selected in1-2 and ss is pressed, 1-2 will not display anything. If other parameter is selected in 1-2, it will display that parameter.

The operation in 1-2 to 1-22, 2-14 to 2-17 and 3-20 to 3-27 are all the same.

E. Example: How to set "LOCK" function





Chapter 4 : Input

AT03 series is designed to accept thermocouples sensor, RTD sensors, linear voltage and linear current inputs. The input type is specified partly through hardware and needs to be specified at the time of ordering.

For sensor inputs (thermocouple and RTD), AT03 can accept K, J, T, R, E, S, B, N or N type thermocouple and Pt100 or JPt100 RTD sensors. There are different segments in firmware to optimize the sensing performance. The specific segment is specified through firmware and is specified through the parameter inP1 under inp submenu.

For linear input, all vairotions are soecified through hardware at the time of ordering.

Input Hardware ordering information

AT- 03- I 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Input
1 = T/C or RTD Sensor
2 = 0~100mV
3 = 0~20mA
4 = 4~20mA
5 = 0~5V
6 = 0~10V
7 = 1~5V
8 = 2~10V
9 = 0~1V

Parameter INP1 under INP submenu

Туре	INP1	°C	°F			
K	K1	0 ~ 200	32 ~ 392			
	K2	0 ~ 400	32 ~ 752			
	K3	0 ~ 800	32 ~ 1472			
	K4	0 ~ 1000	32 ~ 1832			
	K5	0 ~ 1200	32 ~ 2192			
J	J1	0 ~ 200	32 ~ 392			
	J2	0 ~ 400	32 ~ 752			
	J3	0 ~ 800	32 ~ 1472			
	J4	0 ~ 1000	32 ~ 1832			
	J5	0 ~ 1200	32 ~ 2192			
Т	T1	-50 ~ 50	-58 ~ 122			
	T2	-100 ~ 100	-148 ~ 212			
	T3	-200 ~ 400	-328 ~ 752			
R	R	0 ~ 1700	32 ~ 3092			
E	Е	0 ~ 1000	32 ~ 1832			
S	S	0 ~ 1700	32 ~ 3092			
В	В	0 ~ 1800	32 ~ 3272			
N	N	-200 ~ 1300	-328 ~ 2372			
Pt	Pt1	-50 ~ 50	-58 ~ 122			
	Pt2	0 ~ 100	32 ~ 212			
	Pt3	0 ~ 200	32 ~ 392			
	Pt4	0 ~ 400	32 ~ 752			
	Pt5	-200 ~ 600	-328 ~ 1112			
	jPt	-200 ~ 500	-328 ~ 932			
Linear	Lin	-1999	-1999 ~ 9999			

Chapter 5 : Output

AT03 series has highly customizable outputs for customers' specific needs. It may have upto 2 control outputs. The desired ouputs needs to be specified at the time of ordereing and set by the users under OUTPUT submenu according to the hardware.

Output hardware ordering information

A I - 🗆 U 3 - 🗆 🛮					
Output 1	Output 2				
(1 is standard)	0 = None				
1 = Relay	1 = Relay				
2 = Pulsed	2 = Pulsed				
3 = 0~20mA	3 = 0~20mA				
4 = 4~20mA	4 = 4~20mA				
5 = 0~5V	5 = 0~5V				
6 = 0~10V	6 = 0~10V				
7 = 1~5V	7 = 1~5V				
8 = 2~10V	8 = 2~10V				
9 = Motor Control					

Parameter OUTM under OUT submenu

OUTM	Mode
1	Single Output
2	Dual Output
3	Motor Control, A contact
4	Motor Control, B contact
5	Single output with transmitter
6	Single output with soft start

7	Single output with transmitter and soft start
8	Program control
9	Program control with trsnamitter

Chapter 6: Alarm

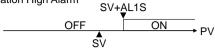
AT03 models can have upto 3 alarms. Each alarm can be programmed to different function and different mode.

Alarm Function

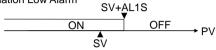
Parameter AL1F, AL2F and AL3F under OUT submenu

ALARM FUNCTION DESCRIPTION					
AL1F	AL2F	AL3F	Description		
0	0	0	No Alarm		
1	1	1	Deviation High Alarm		
2	2	2	Deviation Low Alarm		
3	3	3	Absolute High Alarm		
4	4	4	Absolute Low Alarm		
5	5	5	Deviation high/low Alarm		
6	6	6	Band Alarm		
7	7	7	System Failure Alarm		
8	8	8	Loop break alarm		
9	9	9	Heater Break Alarm		
10	10	10	Segment Ending Alarm		
11	11	11	Program Ending Alarm		
12	12	Not	Time Signal Alarm		
13	13	Availiable	Program Mode Running alarm		

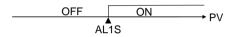
1. Deviation High Alarm



2. Deviation Low Alarm



3. Absolute High Alarm



4. Absolute Low Alarm



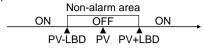
5. Deviation High/Low Alarm

6. Band Alarm

7. System Failure Alarm

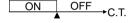
Alarm is triggered when the system has failed.

8. Loop break alarm

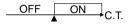


9. Heater Break Alarm

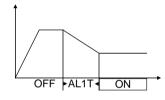
Low or no current flow Control output is ON



Over current or short circuit Control output is OFF



10. Segment Ending Alarm



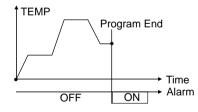
AL1S

1~8 segment

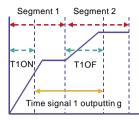
AL1T

0.00 Flicker alarm
(other) ON delay time
99.59 Continuous alarm

11. Program Ending Alarm



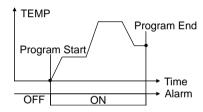
12. Time Signal Alarm



T1SS
Time signal 1 start segment setting
T1ON
Time signal 1 on time setting
T1ES
Time signal 1 end segment setting
T1OF

Time signal 1 off time setting

13. Program Mode Running alarm



Alarm Mode

Parameter AL1M, AL2M and AL3M under OUT submenu

	ALARM MODE DESCRIPTION						
AL1M	AL2M	AL3M	Descrition				
0	0	0	Normal				
1	1	1	Alarm with nomally closed contact				
2	2	2	Latch				
3	3	3	Alarm with nomally closed contact and latch				

	ALARM MODE DESCRIPTION (continue)					
4	4	4	Alarm with inhibit			
5	5	5	Alarm with inhibit and normally closed contact			
6	6	6 6 Alarm with inhibit and latch				
7	7	7	Alarm with inhibit, normally closed contact and latch			
8	(Mode 8, 9,		Alarm with on-delay timer			
9	10, 11 are not availiable on Alarm2 and		Alarm with on-delay timer but normally closed contact			
10	Alarm3. Only		/a		Alarm with soaking timer	
11	Alarm1 has all 11 modes)				Alarm with soaking timer but normally cloased contact	

Chapter 7 : Communication

AT03 has optional RS-232 and RS-485 module, which enables the controller to be programmed and monitored remotely.

Interface RS-232, RS-485

Baud Rate 2400 bps, 4800 bps, 9600 bps, 19200bps, 38400 bps

Data Format ModBus protocol RTU mode



Sample Commands

RTU Request: Read command

0	1	2	3	4	5	6	7
Station Number	Function 0X03	Address (MSB~LSE	3)	Count (MSB~LSE	3)	CRC16 (LSB~MSE	3)

Station number: 00H ~ 1FH

Adderss: 0000H ~ 0100H

Count: number of data

CRC16: Cyclical Redundancy Check

RTU Response: Read command

0	1	2	3	4	5	6
Station	Function	Byte	Data 1		Data 2	SB)
Number	0x03	Count	(MSB~LSB)		(MSB~LS	

Station number: 00H ~ 1FH

Adderss: 0000H ~ 0100H

Count: number of data bytes

CRC16: Cyclical Redundancy Check

RTU Request: Write command

0	1	2	3	4	5	6	7
Station Number	Function 0X06	Address (MSB~LSE	3)	Count (MSB~LSE	3)	CRC16 (LSB~MSE	3)

Station number: 00H ~ 1FH

Adderss: 0000H ~ 0100H

CRC16: Cyclical Redundancy Check

RTU Request: Write command

0	1	2	3	4	5	6	7
Station	Function	Address		Count		CRC16	
Number	0X06	(MSB~LSB)		(MSB~LSB)		(LSB~MSB)	

Station number: 00H ~ 1FH

Adderss : 0000H ~ 0100H

CRC16: Cyclical Redundancy Check

Parameters and Addresses

The following table on the next two pages lists all the parameters and their corresponding addresses under ModBus RTU.

PARAMETERS AND ADDRESSES								
LEvL	00	rPtm	18	AL1F	30	t2On	48	
LoCK	01	P1	19	AL1H	31	t2ES	49	
Sv	02	i1	1A	Al1t	32	t2oF	4A	
OutL	03	d1	1B	AL1m	33	inP1	4B	
At	04	Ct1	1C	AL2F	34	LoSP	4C	
mAn	05	HSt1	1D	AL2H	35	HiSP	4D	
AL1S	06	AotF	1E	AL2t	36	LoAn	4E	
AL1L	07	Ar	1F	AL2m	37	HiAn	4F	
AL1U	08	P2	20	AL3F	38	A1LS	50	
AL2S	09	i2	21	AL3H	39	A1HS	51	
AL2L	0A	d2	22	AL3t	ЗА	unit	52	
AL2U	0B	Ct2	23	AL3m	3B	dp	53	
AL3S	0C	HSt2	24	Act	3C	FiLt	54	
AL3L	0D	db	25	Outm	3D	inP2	55	
AL3U	0E	SSv	26	O1LS	3E	A2LS	56	
SOAK	0F	Sout	27	O1HS	3F	A2HS	57	
rAmP	10	Stme	28	AO	40			
PvoF	11	rUCy	29	O2LS	41	bAud	59	
Pvrr	12	rPtm	2A	O2HS	42	Addr	5A	
SvoF	13	StAt	2B	t1SS	43	LEv1	5B	
Ct	14	PvSt	2C	t1On	44	LEv2	5C	
HbA	15	wAit	2D	t1ES	45	Lev3	5D	
LbA	16	Pid	2E	t1oF	46	LvSL	5E	
Lbd	17	EndP	2F	t2SS	47	L1P1	5F	

PARAMETERS AND ADDRESSES							
L1i1	60	L4P2	78	Sv7	90	1-20	A8
L1d1	61	L4i2	79	tP7	91	1-21	A9
L1Ar	62	L4d2	7A	tS7	92	1-22	AA
L1P2	63	SEG	7B	Sv8	93	2-14	AB
L1i2	64	TimE	7C	tP8	94	2-15	AC
L1d2	65	EndS	7D	tS8	95	2-16	AD
L2P1	66	Sv1	7E	1-2	96	2-17	AE
L2i1	67	tP1	7F	1-3	97	3-20	AF
L2d1	68	ts1	80	1-4	98	3-21	В0
L2Ar	69	Sv2	81	1-5	99	3-22	B1
L2P2	6A	tP2	82	1-6	9A	3-23	B2
L2i2	6B	tS2	83	1-7	9B	3-24	В3
L2d2	6C	Sv3	84	1-8	9C	3-25	B4
L3P1	6D	tP3	85	1-9	9D	3-26	B5
L3i1	6E	tS3	86	1-10	9E	3-27	В6
L3d1	6F	Sv4	87	1-11	9F	Pv	100
L3Ar	70	tP4	88	1-12	A0		
L3p2	71	tS4	89	1-13	A1		
L3i2	72	Sv5	8A	1-14	A2		
L3d2	73	tP5	8B	1-15	А3		
L4P1	74	tS5	8C	1-16	A4		
L4i1	75	Sv6	8D	1-17	A5		
L4d1	76	tP6	8E	1-18	A6		
L4Ar	77	tS6	8F	1-19	A7		

Appendix A Error Code

Input1 error

Input2 error

A/D converter failed

Cold junction compensation failed

PV exceeds set ranges

RAM failed

Interface failed

Auto tuning failed



N0. 19, Lane 202, Fushou St., Xinzhuang Dist., New Taipei City 242, Taiwan Phone : 886-2-2996-3202 Fax : 886-2-2996-2017

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